MOS INTEGRATED CIRCUIT $\mu PD3729$

5000 PIXELS \times 3 COLOR CCD LINEAR IMAGE SENSOR

The μ PD3729 is a high-speed and high sensitive color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The μ PD3729 has 3 rows of 5000 pixels, and it is a 2-output/color type CCD sensor with 2 rows/color of charge transfer register, which transfers the photo signal electrons of 5000 pixels separately in odd and even pixels. Therefore, it is suitable for 400 dpi/A3 high-speed color digital copiers and so on.

FEATURES

NEC

- Valid photocell $: 5000 \text{ pixels} \times 3$
- Photocell's pitch : 10 μ m
- Line spacing : 40 μm (4 lines) Red line-Green line, Green line-Blue line
- Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10⁷ lx•hour)
- Resolution : 16 dot/mm (400 dpi) A3 (297 × 420 mm) size (shorter side)
- Drive clock level : CMOS output under 5 V operation
- Data rate : 30 MHz MAX. (15 MHz/1 output)
- Output type : 2 outputs in phase/color
- Power supply : +12 V
- On-chip circuits : Reset feed-through level clamp circuits
 Voltage amplifiers

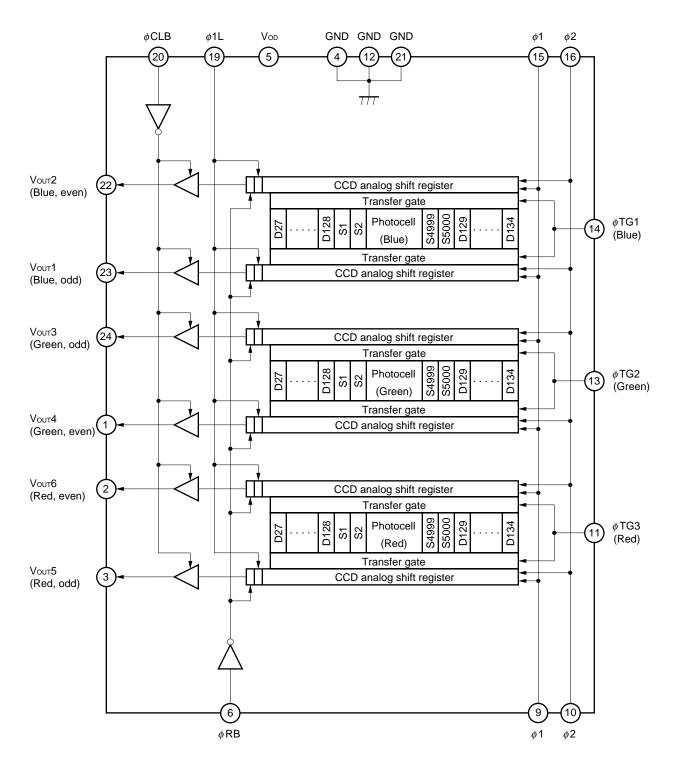
ORDERING INFORMATION

 Part Number
 Package

 μPD3729D
 CCD linear image sensor 24-pin ceramic DIP (400 mil)

The information in this document is subject to change without notice.

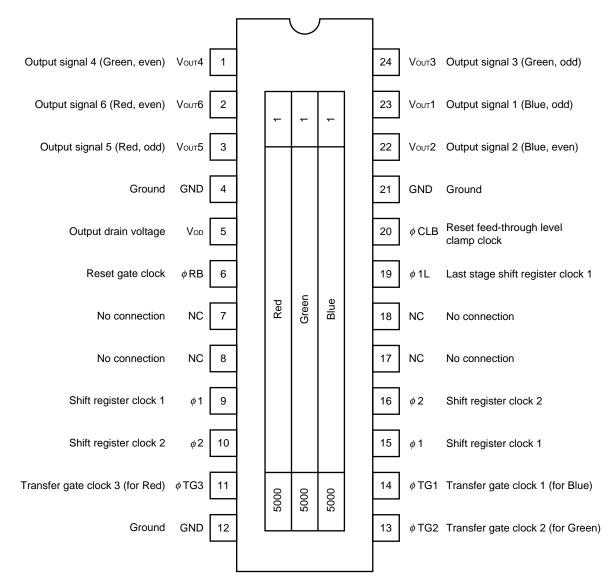
BLOCK DIAGRAM



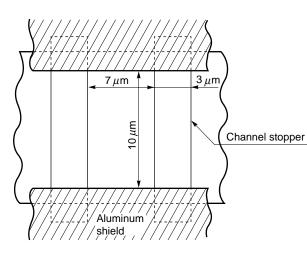
PIN CONFIGURATION (Top View)

CCD linear image sensor 24-pin ceramic DIP (400 mil)

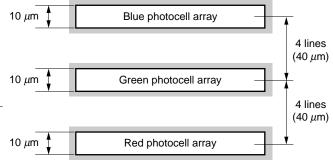
• μPD3729D



PHOTOCELL STRUCTURE DIAGRAM



PHOTOCELL ARRAY STRUCTURE DIAGRAM (Line spacing)



ABSOLUTE MAXIMUM RATINGS (TA = +25 °C)

Parameter	Symbol	Ratings	Unit
Output drain voltage	Vod	-0.3 to +15	V
Shift register clock voltage	Vø1, Vø1L, Vø2	-0.3 to +15	V
Reset gate clock voltage	Vørb	-0.3 to +15	V
Reset feed-through level clamp clock voltage	V _Ø CLB	-0.3 to +15	V
Transfer gate clock voltage	V _Ø тg1 to V _Ø тg3	-0.3 to +15	V
Operating ambient temperature	TA	-25 to +70	°C
Storage temperature	Tstg	-40 to +100	°C

Caution Exposure to ABSOLUTE MAXIMUM RATINGS for extended periods may affect device reliability; exceeding the ratings could cause permanent damage. The parameters apply independently.

RECOMMENDED OPERATING CONDITIONS (TA = +25 °C)

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Output drain voltage	Vod	11.4	12.0	12.6	V
Shift register clock high level	V ₀₁ H, V ₀₁ LH, V ₀₂ H	4.5	5.0	5.5	V
Shift register clock low level	$V_{\phi 1L}, V_{\phi 1LL}, V_{\phi 2L}$	-0.3	0	+0.5	V
Reset gate clock high level	V _{ØRBH}	4.5	5.0	5.5	V
Reset gate clock low level	Vørbl	-0.3	0	+0.5	V
Reset feed-through level clamp clock high level	V _{ØCLBH}	4.5	5.0	5.5	V
Reset feed-through level clamp clock low level	V _Ø CLBL	-0.3	0	+0.5	V
Transfer gate clock high level	V _{øтg1} н to V _{øtg3} н	4.5	V _{¢1H} Note	V _{¢1H} Note	V
Transfer gate clock low level	Vøtg1l to Vøtg3l	-0.3	0	+0.5	V
Data rate	2f _{øRB}	-	2	30	MHz

Note When Transfer gate clock high level ($V_{\phi TG1H}$ to $V_{\phi TG3H}$) is higher than Shift register clock high level ($V_{\phi 1H}$), Image lag can increase.

ELECTRICAL CHARACTERISTICS

(T_A = +25 °C, V_{OD} = 12 V, f_{ØRB} = 1 MHz, data rate = 2 MHz, storage time = 10 ms, light source: 3200 K halogen lamp +C-500S (infrared cut filter, t = 1mm), input signal clock = 5 V_{P-P}

Parameter		Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
Saturation voltage		Vsat		1.5	2.0	-	V
Saturation exposure	Red	SER			0.32		lx•s
	Green	SEG			0.37		lx•s
	Blue	SEB			0.29		lx•s
Photo response non-uni	formity	PRNU	Vout = 1 V		6	18	%
Average dark signal Note	e 1	ADS1	Light shielding		1.0	5.0	mV
		ADS2	-		0.5	5.0	mV
Dark signal non-uniform	ity Note 1	DSNU1	Light shielding		2.0	5.0	mV
		DSNU2			1.0	5.0	mV
Power consumption		Pw			500	700	mW
Output impedance		Zo			0.3	0.5	kΩ
Response	Red	RR		4.3	6.2	8.1	V/lx•s
	Green	Rg		3.8	5.4	7.0	V/lx•s
	Blue	Rв		4.7	6.8	8.9	V/lx•s
Image lag Note 1		IL1	Vout = 1 V		2.0	5.0	%
		IL2	-		1.0	5.0	%
Offset level Note 2		Vos		4.0	5.0	6.0	V
Output fall delay time No	ote 3	ta	Vout = 1 V		25		ns
Register imbalance		RI	Vout = 1 V	0		4.0	%
Total transfer efficiency		TTE	Vout = 1 V,	95	98		%
			data rate = 30 MHz				
Response peak	Red				630		nm
	Green				540		nm
	Blue				460		nm
Dynamic range Note 1		DR11	Vsat /DSNU1		1000		times
		DR12	Vsat/DSNU2		2000		times
		DR21	V _{sat} /σ1		2000		times
		DR22	Vsat/o2		4000		times
Reset feed-through nois	e Note 2	RFTN	Light shielding	-500	+200	+500	mV
Random noise Note 1		σ1	Light shielding	-	1.0	_	mV
		σ2	1	_	0.5	_	mV

Notes 1. ADS1, DSNU1, IL1, DR11 and DR21 show the specification of Vour1 and Vour2. ADS2, DSNU2, IL2, DR12 and DR22 show the specification of Vour3 to Vour6.

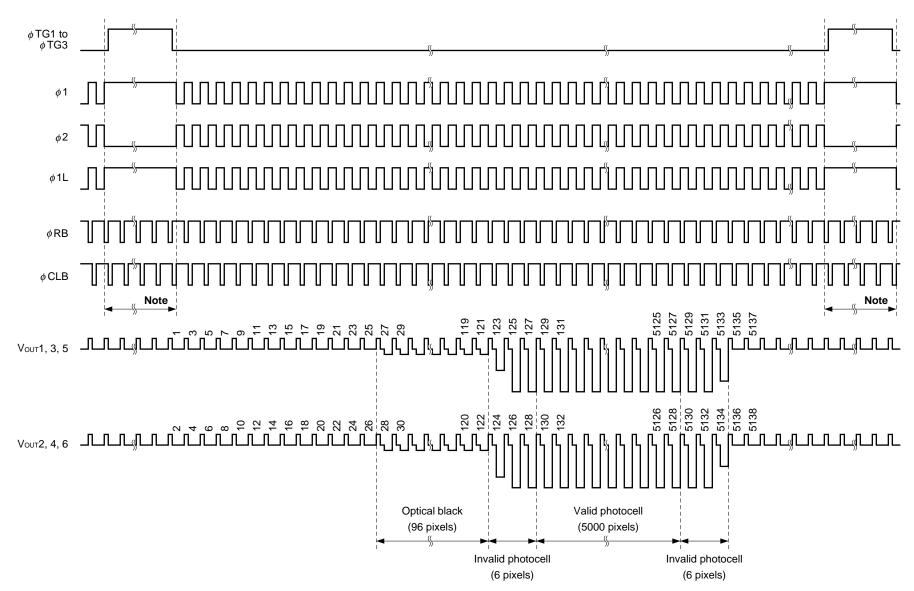
- 2. Refer to TIMING CHART 2.
- **3.** When the fall time of ϕ 1L (t2') is the TYP. value (refer to **TIMING CHART 2**).

INPUT PIN CAPACITANCE (TA = +25 $^{\circ}$ C, Vod = 12 V)

Parameter	Symbol	Pin name	Pin No.	MIN.	TYP.	MAX.	Unit
Shift register clock pin capacitance 1	C _{ø1}	<i>φ</i> 1	9		500	800	pF
			15		500	800	pF
Shift register clock pin capacitance 2	C _{¢2}	φ2	10		500	800	pF
			16		500	800	pF
Last stage shift register clock pin capacitance	CøL	<i>φ</i> 1L	19		50		pF
Reset gate clock pin capacitance	Cørb	φRB	6		50		pF
Reset feed-through level clamp clock pin capacitance	Cøclb	φCLB	20		50		pF
Transfer gate clock pin capacitance	Cøtg	φTG1	14		70		pF
		φTG2	13		70		pF
		φTG3	11		70		pF

Remark Pins 9 and 15 (ϕ 1), 10 and 16 (ϕ 2) are each connected inside of the device.

TIMING CHART 1 (for each color)

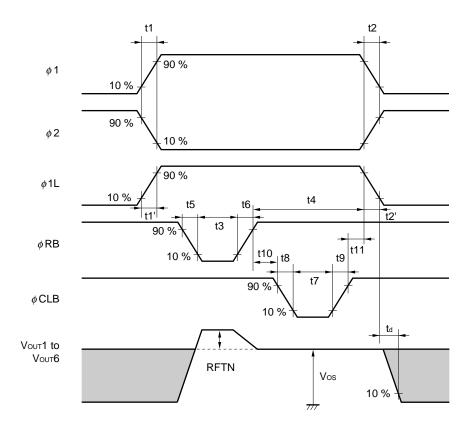


Note Input the ϕ RB and ϕ CLB pulses continuously during this period, too.

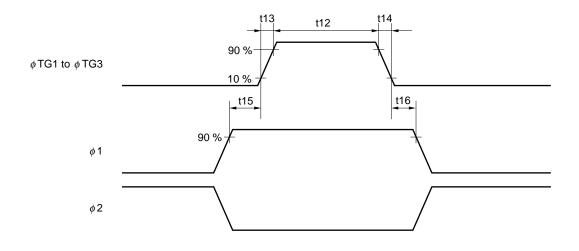
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TIMING CHART 2 (for each color)



 ϕ TG1 to ϕ TG3, ϕ 1, ϕ 2 TIMING CHART

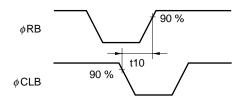


φ 1

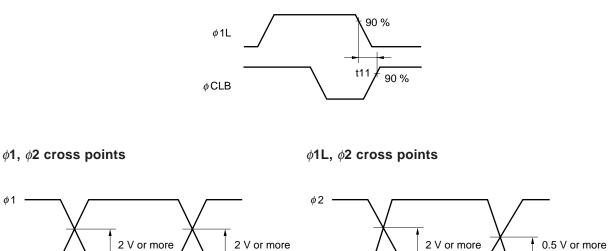
φ2

Symbol	MIN.	TYP.	MAX.	Unit
t1, t2	0	50		ns
t1', t2'	0	5		ns
t3	20	50		ns
t4	20	100	-	ns
t5, t6	0	20		ns
t7	20	150		ns
t8, t9	0	20		ns
t10	-10 ^{Note 1}	+50	-	ns
t11	_5Note 2	+50		ns
t12	5000	10000		ns
t13, t14	0	50		ns
t15, t16	900	1000		ns

Notes 1. MIN. of t10 shows that the ϕ RB and ϕ CLB overlap each other.



2. MIN. of t11 shows that the ϕ 1L and ϕ CLB overlap each other.



φ1L

Remark Adjust cross points (ϕ 1, ϕ 2) and (ϕ 1L, ϕ 2) with input resistance of each pin.

DEFINITIONS OF CHARACTERISTIC ITEMS

- Saturation voltage: V_{sat}
 Output signal voltage at which the response linearity is lost.
- Saturation exposure: SE Product of intensity of illumination (Ix) and storage time (s) when saturation of output voltage occurs.
- 3. Photo response non-uniformity: PRNU

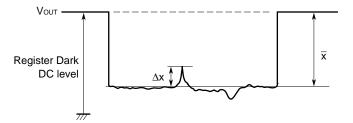
The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. This is calculated by the following formula.

PRNU (%) =
$$\frac{\Delta x}{\overline{x}} \times 100$$

 Δx : maximum of $|x_j - \overline{x}|$
 $\sum_{x_i}^{5000} x_i$

$$\overline{\mathbf{x}} = \frac{\sum_{j=1}^{x_j} x_j}{5000}$$

x_j : Output voltage of valid pixel number j



4. Average dark signal: ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula.

ADS (mV) =
$$\frac{\sum_{j=1}^{5000} d_j}{5000}$$

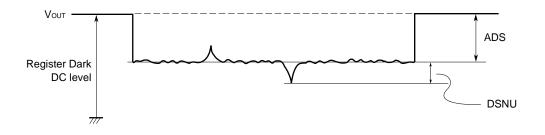
dj : Dark signal of valid pixel number j

5. Dark signal non-uniformity: DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula.

DSNU (mV) : maximum of $|d_j - ADS|_{j=1 \text{ to 5000}}$

 $d_j: \text{Dark signal of valid pixel number } j$

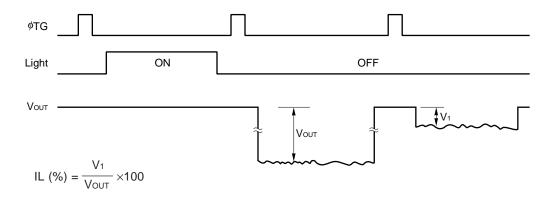


- Output impedance: Zo
 Impedance of the output pins viewed from outside.
- 7. Response: R

Output voltage divided by exposure (Ix-s). Note that the response varies with a light source (spectral characteristic).

8. Image lag: IL

The rate between the last output voltage and the next one after read out the data of a line.



9. Register imbalance: RI

The rate of the difference between the averages of the output voltage of Odd and Even pixels, against the average output voltage of all the valid pixels.

RI (%) =
$$\frac{\frac{2}{n} \left| \sum_{j=1}^{n} (V_{2j-1} - V_{2j}) \right|}{\frac{1}{n} \sum_{j=1}^{n} V_{j}} \times 100$$

n : Number of va

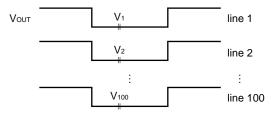
n : Number of valid pixels V_j : Output voltage of each pixel

10. Random noise: σ

Random noise σ is defined as the standard deviation of a valid pixel output signal with 100 times (=100 lines) data sampling at dark (light shielding).

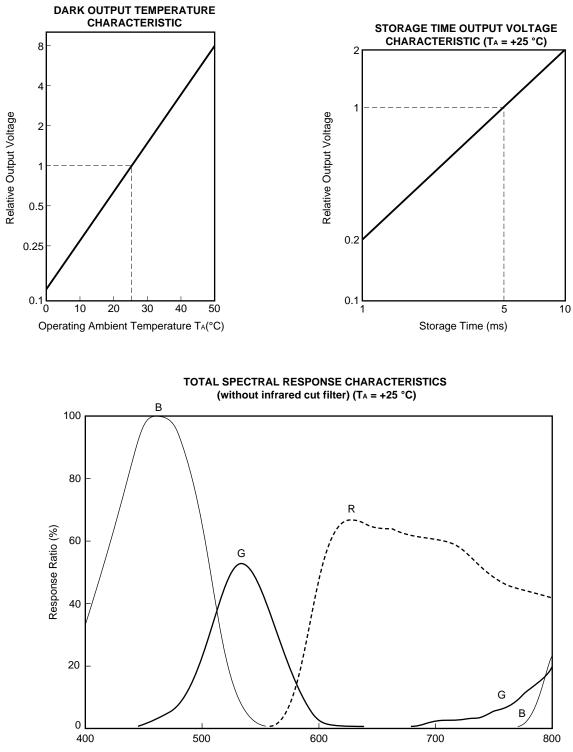
$$\sigma (mV) = \sqrt{\frac{\sum_{i=1}^{100} (V_i - \overline{V})^2}{100}} \quad , \ \overline{V} = \frac{1}{100} \sum_{i=1}^{100} V_i$$

Vi: A valid pixel output signal among all of the valid pixels for each color



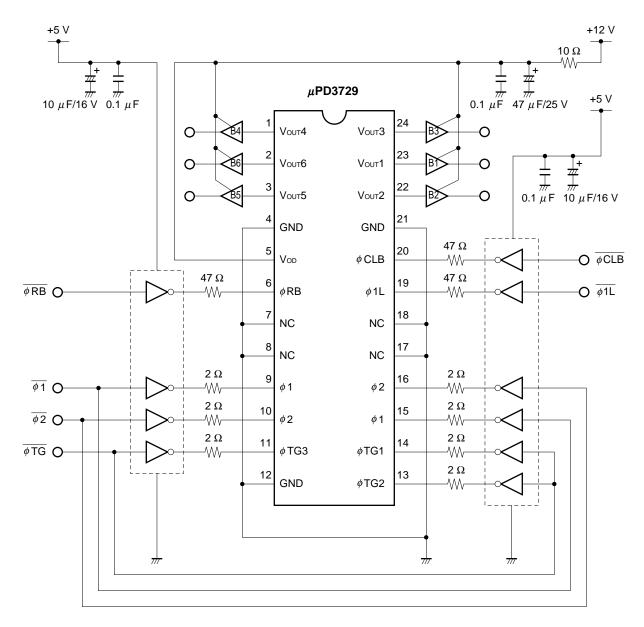
This is measured by the DC level sampling of only the signal level, not by CDS (Correlated Double Sampling).

STANDARD CHARACTERISTIC CURVES

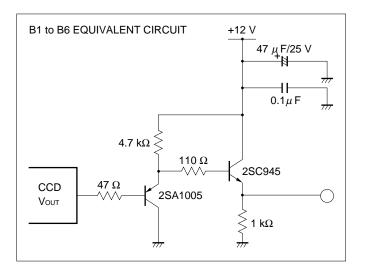


Wavelength (nm)

APPLICATION CIRCUIT EXAMPLE



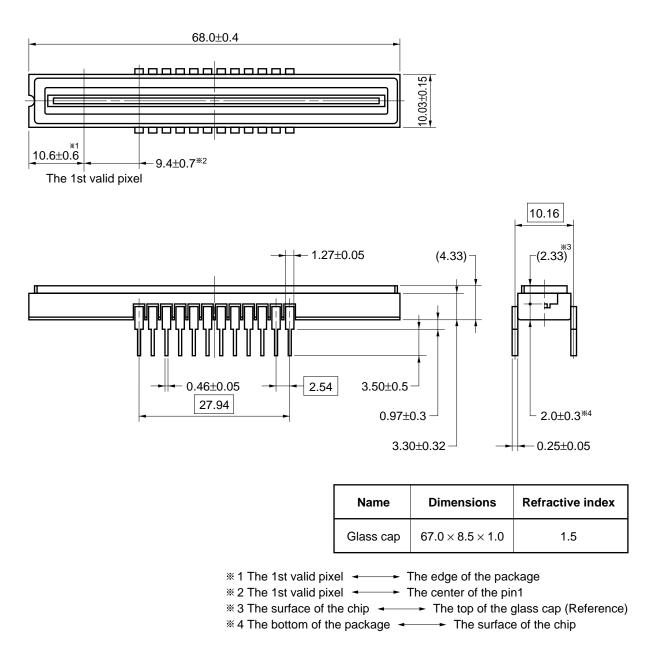
Remark The inverters shown in the above application circuit example are the 74AC04.



PACKAGE DRAWING

CCD LINEAR IMAGE SENSOR 24-PIN CERAMIC DIP (400mil)

(Unit : mm)



24D-1CCD-PKG1-1

RECOMMENDED SOLDERING CONDITIONS

When soldering this product, it is highly recommended to observe the conditions as shown below.

If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

For more details, refer to our document "Semiconductor Device Mounting Technology Manual"(C10535E).

Type of Through-hole Device

μ PD3729D: CCD linear image sensor 24-pin ceramic DIP (400 mil)

Process	Conditions	
Partial heating method	Pin temperature: 300 °C or below, Heat time: 3 seconds or less (per pin)	

[MEMO]

[MEMO]

-NOTES FOR CMOS DEVICES -

① PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note: Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

(2) HANDLING OF UNUSED INPUT PINS FOR CMOS

Note: No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS device behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

③ STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note: Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee outpin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function. [MEMO]

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The application circuits and their parameters are for reference only and are not intended for use in actual design-ins.

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While NEC Corporation has been making continuous effort to enhance the reliability of its semiconductor devices, the possibility of defects cannot be eliminated entirely. To minimize risks of damage or injury to persons or property arising from a defect in an NEC semiconductor device, customers must incorporate sufficient safety measures in its design, such as redundancy, fire-containment, and anti-failure features.

NEC devices are classified into the following three quality grades:

"Standard", "Special", and "Specific". The Specific quality grade applies only to devices developed based on a customer designated "quality assurance program" for a specific application. The recommended applications of a device depend on its quality grade, as indicated below. Customers must check the quality grade of each device before using it in a particular application.

- Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots
- Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)
- Specific: Aircrafts, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

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Anti-radioactive design is not implemented in this product.